

$$\begin{aligned}
T(S, V, N) &= \left(\frac{\partial U}{\partial S} \right)_{V, N} & p(S, V, N) &= - \left(\frac{\partial U}{\partial V} \right)_{S, N} & \left(\frac{\partial \mu}{\partial T} \right)_p &= -S_m & \mu_i(S, V, N) &= \left(\frac{\partial U}{\partial n_i} \right)_{S, V, n_{j \neq i}} \\
\frac{1}{T}(U, V, N) &= \left(\frac{\partial S}{\partial U} \right)_{V, N} & \frac{p}{T}(U, V, N) &= \left(\frac{\partial S}{\partial V} \right)_{U, N} & \frac{\mu_i}{T}(U, V, N) &= - \left(\frac{\partial S}{\partial n_i} \right)_{U, V, n_{j \neq i}} \\
c_p &= \frac{T}{n} \left(\frac{\partial S}{\partial T} \right)_{p, n} = \frac{1}{n} \left(\frac{\partial H}{\partial T} \right)_{p, n} & \Delta H = Q &= c_p n \Delta T & c_v &= \frac{T}{n} \left(\frac{\partial S}{\partial T} \right)_{V, n} = \frac{1}{n} \left(\frac{\partial U}{\partial T} \right)_{V, n} & Q &= c_v n \Delta T \\
\alpha &= \frac{1}{V} \left(\frac{\partial V}{\partial T} \right)_{p, n} = \frac{1}{v} \left(\frac{\partial v}{\partial T} \right)_{p, n} & \frac{\Delta V}{V} &= \alpha \Delta T & \kappa_T &= \frac{-1}{V} \left(\frac{\partial V}{\partial p} \right)_{T, n} = \frac{-1}{v} \left(\frac{\partial v}{\partial p} \right)_{T, n} & \frac{\Delta V}{V} &= \kappa_T \Delta p \\
G &= H - TS & H &= U + pV & F &= U - TS & \Delta \mu &= V_m \Delta p & \frac{dp}{dT} &= \frac{\Delta_{trs} S}{\Delta_{trs} V} & \frac{dp}{dT} &= \frac{\Delta_{trs} H}{T \Delta_{trs} V} \\
\frac{d \ln p}{dT} &= \frac{\Delta_{trs} H}{RT^2} & \frac{d \ln p}{d \frac{1}{T}} &= - \frac{\Delta H}{R} & \ln \frac{p}{p_0} &= - \frac{\Delta H}{R} \left(\frac{1}{T} - \frac{1}{T_0} \right) & p &= p_A + p_B & p_A &= x_A p_A^* \\
p_A &= x_A K_A & p &= x_A \cdot p_A^* + x_B \cdot p_B^* = p_B^* + x_A (p_A^* - p_B^*) & p &= \left(\frac{y_A}{p_A^*} + \frac{y_B}{p_B^*} \right)^{-1} = \frac{p_A^* p_B^*}{p_A^* + y_A (p_B^* - p_A^*)} \\
n_\alpha \cdot l_\alpha &= n_\beta \cdot l_\beta & \mu_A^*(g) &= \mu_A^*(l) + RT \ln x_A & \ln(1 - x_B) &= \frac{\Delta_{vap} H}{R} \left(\frac{1}{T} - \frac{1}{T^*} \right) & x_B &= \frac{\Delta_{vap} H}{R} \frac{\Delta T}{T^{*2}} \\
\Delta T &= K_b m_B & K_b &= \frac{RT^{*2}}{\Delta_{vap} H} M & \ln(1 - x_B) &= \frac{\Delta_{fus} H}{R} \left(\frac{1}{T} - \frac{1}{T^*} \right) & \Delta T &= K_f m_B & K_f &= \frac{RT^{*2}}{\Delta_{fus} H} M \\
\ln x_B &= - \frac{\Delta_{fus} H}{R} \left(\frac{1}{T} - \frac{1}{T^*} \right) & \Pi &= cRT & p_{in} &= p_{out} + \frac{2\gamma}{r} & p &= p^* \exp \left(\frac{2\gamma_m}{rRT} \right) \\
\rho g h &= \frac{2\gamma}{r} \cos \vartheta & X_i &= \left(\frac{\partial X}{\partial n_i} \right)_{T, p, n_j} & \Delta G_{mix} &= RT \sum_i n_i \ln a_i & \Delta S_{mix} &= -T \sum_i n_i \ln a_i \\
\Delta_r G^\circ &= -RT \ln K & \Delta_r G &= \Delta_r G^\circ + RT \ln Q & \frac{d \ln K}{d \frac{1}{T}} &= - \frac{\Delta_r H^\circ}{R} & \ln \frac{K_1}{K_2} &= - \frac{\Delta_r H^\circ}{R} \left(\frac{1}{T_1} - \frac{1}{T_2} \right) \\
\frac{1}{A} \frac{\partial n_i}{\partial t} &= -D_i \frac{\partial c_i}{\partial z} & \frac{1}{A} \frac{\partial Q}{\partial t} &= -\kappa \frac{\partial T}{\partial z} & \left(\frac{\partial c}{\partial t} \right) &= D \left(\frac{\partial^2 c}{\partial z^2} \right) & c(t) &= \frac{n_0}{A} \frac{1}{\sqrt{\pi D t}} \exp \left(- \frac{z^2}{4Dt} \right) \\
\langle x^2 \rangle^{\frac{1}{2}} &= \sqrt{2Dt} & \left(\frac{\partial c}{\partial t} \right) &= D \left(\frac{\partial^2 c}{\partial z^2} \right) - v_{k\ddot{o}z\ddot{e}g} \left(\frac{\partial c}{\partial z} \right) & \langle r^2 \rangle^{\frac{1}{2}} &= \sqrt{4Dt} & \langle r^2 \rangle^{\frac{1}{2}} &= \sqrt{6Dt} \\
\eta &= K(\rho_g - \rho_f) t & \frac{dV}{dt} &= \frac{(p_1^2 - p_2^2) \pi r^4}{16 \cdot l \cdot \eta \cdot p_0} & c(t) &= \frac{n_0}{A} \frac{1}{2\sqrt{\pi D t}} \exp \left(- \frac{z^2}{4Dt} \right) & D &= \frac{kT}{6\pi\eta r} \\
\frac{dV}{dt} &= \frac{(p_1 - p_2) \pi r^4}{8 \cdot l \cdot \eta} & dU &= TdS - pdV + \sum_i \mu_i dn_i & dS &= \frac{1}{T} dU + pdV - \sum_i \mu_i dn_i \\
0 &= SdT - VdP + \sum_{i=1}^k \mu_i dn_i & dn_A &= -v_A d\xi & \sum_{i=1}^r v_i A_i &= 0 & \left(\frac{\partial \mu}{\partial p} \right)_T &= V_m & c_v &\equiv \frac{T}{n} \left(\frac{\partial S}{\partial T} \right)_V \\
\Delta U &= Q + W & H &= U + PV & G &= U - TS + PV & dQ &= TdS & dW &= -PdV & F &= U - TS
\end{aligned}$$